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CLAIMS

What is claimed is:

1. A method for deriving barycentric coordinates for a point \mathbf{p} within an n-sided polygon, wherein, for a particular coordinate \mathbf{w}_j , corresponding to a vertex \mathbf{q}_j , the method embodies a formula which may be expressed as follows:

$$W_{j} = \frac{\cot(\gamma_{j}) + \cot(\delta_{j})}{\|\mathbf{p} - \mathbf{q}_{j}\|^{2}}$$

where δ_i and γ_i are adjacent angles to the edge pq_i at the vertex q_i .

- 2. The method of claim 1 tangibly embodied on or in a memory.
- 3. The method of claim 2 wherein a series of instructions or program code embodying the method is stored in a memory.
- 4. A method for deriving weights w_{ij} for expressing a vertex \mathbf{q}_i in a mesh representation of an object surface in terms of its one-ring neighbors \mathbf{q}_j , $\forall j \in N(i)$, wherein, for a particular weight w_{ij} , corresponding to a vertex \mathbf{q}_j , the method embodies a formula which may be expressed as follows:

$$w_{ij} = \frac{\cot(\gamma_j) + \cot(\delta_j)}{\|\mathbf{q_i} - \mathbf{q_j}\|^2}$$

where δ_i and γ_i are adjacent angles to the edge $\mathbf{q}_i\mathbf{q}_i$ at the vertex \mathbf{q}_i .

- 5. The method of claim 4 tangibly embodied on or in a memory.
- 6. The method of claim 5 wherein a series of instructions or program code embodying the method is stored in a memory.
- 7. A method of parameterizing a mesh representation of an object surface comprising the steps of:

for one or more vertices $\mathbf{q_i}$ of the mesh representation, computing for one or more of its one-ring neighbors $\mathbf{q_j}$, $\forall j \in N(i)$, a weight $\mathbf{w_{ij}}$ in accordance with the following formula:

$$w_{ij} = \frac{\cot(y_j) + \cot(\delta_j)}{\|\mathbf{q}_i - \mathbf{q}_i\|^2}$$

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where δ_j and γ_j are adjacent angles to the edge $\mathbf{q}_i\mathbf{q}_j$ at the vertex \mathbf{q}_j ; and

responsive to one or more of the weights w_{ij} determined in the foregoing step, determining the parameterized coordinates of one or more of the vertices of the mesh representation.

- 8. The method of claim 7 further comprising fixing the positions of one or more boundary vertices in parameter space.
- 9. The method of claim 8 further comprising assigning each of these vertices a position on a fixed boundary C, where the position on the fixed boundary C assigned to a vertex i may be referred to as C_{u_i} .
- 10. The method of claim 9 further comprising solving the following system of linear equations in order to derive the parameterization of the mesh representation:

$$\forall i, i \in [1...n], \begin{cases} \sum_{j \in N(i)} w_{ij} (\mathbf{u_i} - \mathbf{u_j}) = 0 & \text{if } i \text{ is an interior vertex} \\ \mathbf{u_i} = \mathbf{C_{u_i}} & \text{if } i \text{ is a boundary vertex} \end{cases}$$

where \mathbf{u}_i is the vertex i in parameter space (and \mathbf{u}_i is the vertex j in parameter space), and $\mathbf{C}_{\mathbf{u}_i}$ is the boundary position in parameter space assigned to the boundary vertex i.

11. A method of parameterizing a mesh representation of an object surface comprising the steps of:

a step for computing, for one or more vertices $\mathbf{q_i}$ of the mesh representation and one or more of its one-ring neighbors $\mathbf{q_j}$, $\forall j \in N(i)$, a weight $\mathbf{w_{ij}}$ in accordance with the following formula:

$$w_{ij} = \frac{\cot(\gamma_j) + \cot(\delta_j)}{\|\mathbf{q}_i - \mathbf{q}_j\|^2}$$

where δ_j and γ_j are adjacent angles to the edge q_iq_j at the vertex $q_j;$ and

a step for determining, responsive to one or more of the weights w_{ij} determined in the foregoing step, the parameterized coordinates of one or more of the vertices of the mesh representation.

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- 12. The methods of any of claims 1-11 tangibly embodied on or in a memory.
- 13. The memory of claim 12 wherein the method is embodied as a series of instructions or program code stored in the memory.